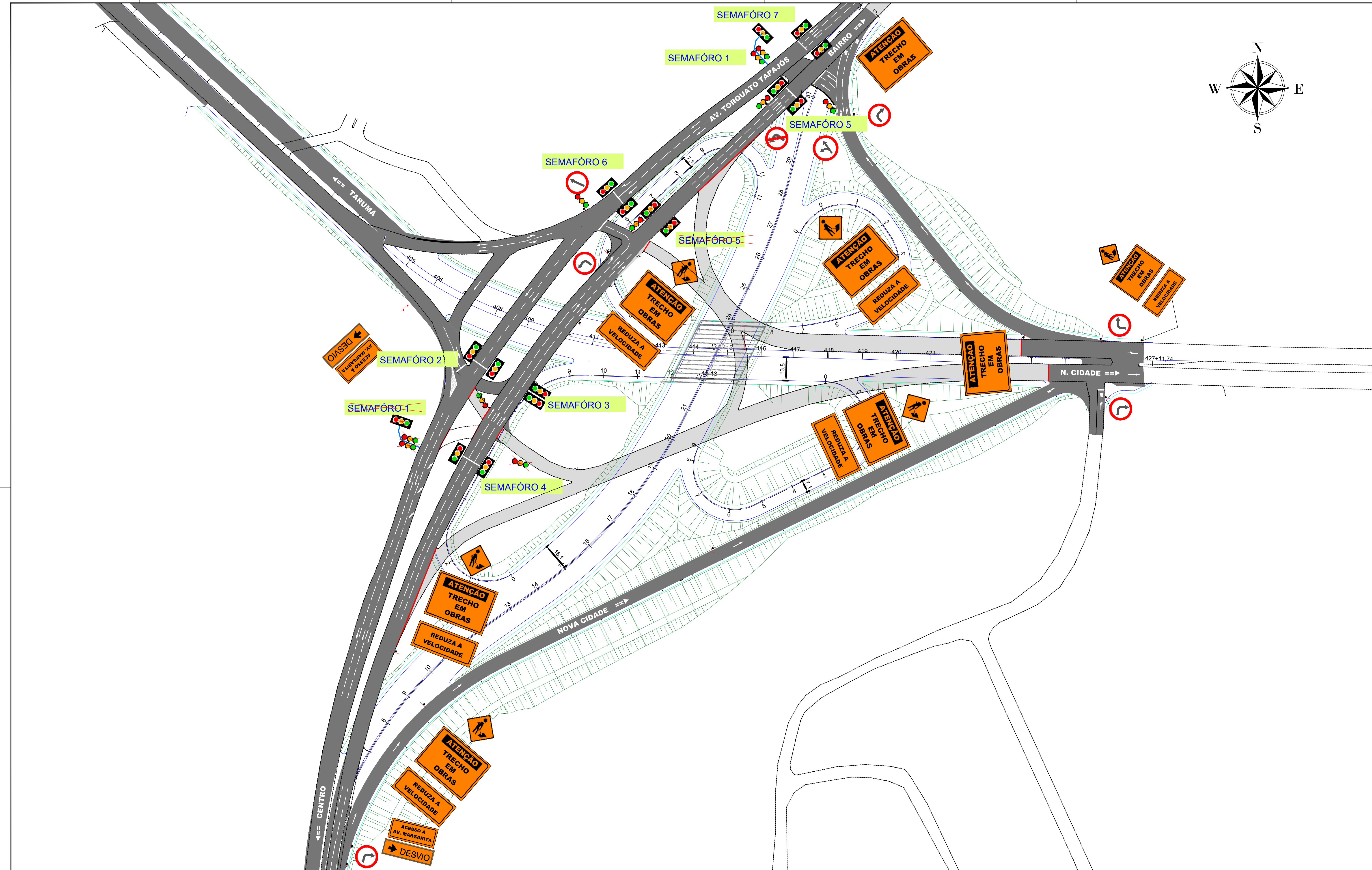




 TRECHO DE DESVIO

 BARREIRA DE CONCRETO

1. Sistema de Coordenadas RTM;

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00	EMISSAO INICIAL	09/07/2019
No.	DESCRIÇÃO	DATA
R E V I S Õ E S		

A schematic diagram of a 2D articulated robot arm. It consists of a fixed base (grey rectangle) connected to three segments by revolute joints. Each segment is represented by a rectangle with a black line indicating its internal structure. The joints are marked with red dots. The end effector is a gripper, represented by two black rectangles.

APROVAÇÃO

ESCALA : 1:2 000	DATA : JUN/2020	ÁREA : _____	REVISÃO : 00
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PRANCHA :
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